1 Object Oriented Programming

In a previous lecture, you were introduced to the programming paradigm known as Object-Oriented Programming (OOP). OOP allows us to treat data as objects - like we do in real life.

For example, consider the class **Student**. Each of you as individuals is an instance of this class. So, a student **Angela** would be an instance of the class **Student**.

Details that all CS 61A students have, such as **name**, are called instance attributes. Every student has these attributes, but their values differ from student to student. An attribute that is shared among all instances of **Student** is known as a class attribute. An example would be the **students** attribute; the number of students that exist is not a property of any given student but rather of all of them.

All students are able to do homework, attend lecture, and go to office hours. When functions belong to a specific object, they are said to be methods. In this case, these actions would be bound methods of **Student** objects.

Here is a recap of what we discussed above:

- **class**: a template for creating objects
- **instance**: a single object created from a class
- **instance attribute**: a property of an object, specific to an instance
- **class attribute**: a property of an object, shared by all instances of a class
- **method**: an action (function) that all instances of a class may perform
Questions

1.1 Below we have defined the classes Professor and Student, implementing some of what was described above. Remember that we pass the self argument implicitly to instance methods when using dot-notation. There are more questions on the next page.

class Student:
    students = 0  # this is a class attribute
    def __init__(self, name, ta):
        self.name = name  # this is an instance attribute
        self.understanding = 0
        Student.students += 1
        print("There are now", Student.students, "students")
        ta.add_student(self)

    def visit_office_hours(self, staff):
        staff.assist(self)
        print("Thanks, " + staff.name)

class Professor:
    def __init__(self, name):
        self.name = name
        self.students = {}

    def add_student(self, student):
        self.students[student.name] = student

    def assist(self, student):
        student.understanding += 1

Note: This worksheet is a problem bank—most TAs will not cover all the problems in discussion section.
What will the following lines output?

```python
>>> snape = Professor("Snape")
>>> harry = Student("Harry", snape)

>>> harry.visit_office_hours(snape)

>>> harry.visit_office_hours(Professor("Hagrid"))

>>> harry.understanding

>>> [name for name in snape.students]

>>> x = Student("Hermione", Professor("McGonagall")).name

>>> x

>>> [name for name in snape.students]
```
1.2 We now want to write three different classes, Server, Client, and Email to simulate email. Fill in the definitions below to finish the implementation! There are more methods to fill out on the next page.

*We suggest that you approach this problem by first filling out the Email class, then fill out the register_client method of Server, then implement the Client class, and lastly fill out the send method of the Server class.*

```python
class Email:
    """Every email object has 3 instance attributes: the message, the sender name, and the recipient name."
    ""
    def __init__(self, msg, sender_name, recipient_name):


class Server:
    """Each Server has an instance attribute clients, which is a dictionary that associates client names with client objects."
    ""
    def __init__(self):
        self.clients = {}

    def send(self, email):
        """Take an email and put it in the inbox of the client it is addressed to."
        ""

    def register_client(self, client, client_name):
        """Takes a client object and client_name and adds them to the clients instance attribute."
        ""
```

*Note: This worksheet is a problem bank—most TAs will not cover all the problems in discussion section.*
class Client:
    """Every Client has instance attributes name (which is used for addressing emails to the client), server (which is used to send emails out to other clients), and inbox (a list of all emails the client has received)."""

    def __init__(self, server, name):
        self.inbox = []

    def compose(self, msg, recipient_name):
        """Send an email with the given message msg to the given recipient client."""

    def receive(self, email):
        """Take an email and add it to the inbox of this client."""
2 Inheritance

Python classes can implement a useful abstraction technique known as inheritance. To illustrate this concept, consider the following Dog and Cat classes.

```python
class Dog():
    def __init__(self, name, owner):
        self.is_alive = True
        self.name = name
        self.owner = owner
    def eat(self, thing):
        print(self.name + " ate a " + str(thing) + "!")
    def talk(self):
        print(self.name + " says woof!")

class Cat():
    def __init__(self, name, owner, lives=9):
        self.is_alive = True
        self.name = name
        self.owner = owner
        self.lives = lives
    def eat(self, thing):
        print(self.name + " ate a " + str(thing) + "!")
    def talk(self):
        print(self.name + " says meow!")
```

Notice that because dogs and cats share a lot of similar qualities, there is a lot of repeated code! To avoid redefining attributes and methods for similar classes, we can write a single superclass from which the similar classes inherit. For example, we can write a class called Pet and redefine Dog as a subclass of Pet:

```python
class Pet():
    def __init__(self, name, owner):
        self.is_alive = True  # It's alive!!!
        self.name = name
        self.owner = owner
    def eat(self, thing):
        print(self.name + " ate a " + str(thing) + "!")
    def talk(self):
        print(self.name)

class Dog(Pet):
    def talk(self):
        print(self.name + ' says woof!')
```

Inheritance represents a hierarchical relationship between two or more classes where one class is a more specific version of the other, e.g. a dog is a pet. Because Dog inherits from Pet, we didn’t have to redefine __init__ or eat. However, since we want Dog to talk in a way that is unique to dogs, we did override the talk method.

Note: This worksheet is a problem bank—most TAs will not cover all the problems in discussion section.
Questions

2.1 Below is a skeleton for the Cat class, which inherits from the Pet class. To complete the implementation, override the _init_ and talk methods and add a new lose_life method.

*Hint:* You can call the _init_ method of Pet to set a cat’s name and owner.

```python
class Cat(Pet):
    def _init_(self, name, owner, lives=9):

    def talk(self):
        """Print out a cat's greeting.
        
        >>> Cat('Thomas', 'Tammy').talk()
        Thomas says meow!
        """

    def lose_life(self):
        """Decrements a cat's life by 1. When lives reaches zero, 'is_alive'
        becomes False. If this is called after lives has reached zero, print out
        that the cat has no more lives to lose.
        """
```

*Note: This worksheet is a problem bank—most TAs will not cover all the problems in discussion section.*
More cats! Fill in this implementation of a class called NoisyCat, which is just like a normal Cat. However, NoisyCat talks a lot – twice as much as a regular Cat!

```python
class _________________: # Fill me in!
    """A Cat that repeats things twice."""
    def __init__(self, name, owner, lives=9):
        # Is this method necessary? Why or why not?

    def talk(self):
        """Talks twice as much as a regular cat."

        >>> NoisyCat('Magic', 'James').talk()
        Magic says meow!
        Magic says meow!
        """
```
2.3 (Summer 2013 Final) What would Python display?

class A:
    def f(self):
        return 2
    def g(self, obj, x):
        if x == 0:
            return A.f(obj)
        return obj.f() + self.g(self, x - 1)

class B(A):
    def f(self):
        return 4

>>> x, y = A(), B()
>>> x.f()

>>> B.f()

>>> x.g(x, 1)

>>> y.g(x, 2)
3 Linked Lists

There are many different implementations of sequences in Python. Today, we'll explore the linked list implementation.

A linked list is either an empty linked list, or a Link object containing a first value and the rest of the linked list.

To check if a linked list is an empty linked list, compare it against the class attribute Link.empty:

```python
if link is Link.empty:
    print('This linked list is empty!')
else:
    print('This linked list is not empty!')
```

Implementation

```python
class Link:
    empty = ()
    def __init__(self, first, rest=empty):
        assert rest is Link.empty or isinstance(rest, Link)
        self.first = first
        self.rest = rest

def __repr__(self):
    if self.rest:
        rest_str = ', ' + repr(self.rest)
    else:
        rest_str = ''
    return 'Link(' + repr(self.first) + rest_str + ')

def __str__(self):
    string = '<'
    while self.rest is not Link.empty:
        string += str(self.first) + ' ' + str(self.first) + '>
        self = self.rest
    return string + str(self.first) + '>'
```

Note: This worksheet is a problem bank—most TAs will not cover all the problems in discussion section.
Questions

3.1 Write a function that takes in a linked list and returns the sum of all its elements. You may assume all elements in `lnk` are integers.

```python
def sum_nums(lnk):
    """
    >>> a = Link(1, Link(6, Link(7)))
    >>> sum_nums(a)
    14
    """
```

3.2 Write a function that takes in a Python list of linked lists and multiplies them element-wise. It should return a new linked list.

If not all of the `Link` objects are of equal length, return a linked list whose length is that of the shortest linked list given. You may assume the `Link` objects are shallow linked lists, and that `lst_of_lnks` contains at least one linked list.

```python
def multiply_lnks(lst_of_lnks):
    """
    >>> a = Link(2, Link(3, Link(5)))
    >>> b = Link(6, Link(4, Link(2)))
    >>> c = Link(4, Link(1, Link(0, Link(2))))
    >>> p = multiply_lnks([a, b, c])
    >>> p.first
    48
    >>> p.rest.first
    12
    >>> p.rest.rest.rest is Link.empty
    True
    """
```

3.3 Implement `filter_link`, which takes in a linked list `link` and a function `f` and returns a generator which yields the values of `link` for which `f` returns `True`.

Note: This worksheet is a problem bank—most TAs will not cover all the problems in discussion section.
Try to implement this both using a while loop and without using any form of iteration.

```python
def filter_link(link, f):
    
    >>> link = Link(1, Link(2, Link(3)))
    >>> g = filter_link(link, lambda x: x % 2 == 0)
    >>> next(g)
    2
    >>> next(g)
    StopIteration
    >>> list(filter_link(link, lambda x: x % 2 != 0))
    [1, 3]
    
    while ________________:
        if ________________:
            __________________
            __________________
    
    def filter_no_iter(link, f):
        
        >>> link = Link(1, Link(2, Link(3)))
        >>> list(filter_no_iter(link, lambda x: x % 2 != 0))
        [1, 3]
        
        if ________________:
            return

        elif ________________:
            __________________
            __________________
```

Note: This worksheet is a problem bank—most TAs will not cover all the problems in discussion section.
1. Midterm Review Snax

(a) Two robots are handing out midterm snacks to 61A students who are lined up in the hallway. The left robot can hold $x$ snacks at once, and the right robot can hold $y$ snacks. Both robots can refill their capacity at any given time from a bottomless pit of snacks. However, when one robot (A) goes to refill snacks, the other robot (B) must wait until A returns before B continues handing out snacks. In other words, A and B must both feed a student (in full) on their respective ends of the hallway at the same time. Both robots can refill at the same time.

The list $\text{snax}$ contains the number of snacks that must be given to each student in order for that student to be satisfied. Return the minimum number of refills required for both robots to feed every student in the hallway. You can assume that the individual capacity of each robot is $\geq \max(\text{snax})$, and that each robot cannot move on from its current student until the student has been satisfied.

```python
def feed(snax, x, y):
    
    >>> feed([1, 1, 1], 2, 2) # The two robots both refill once at the beginning
    2
    >>> feed([1, 2, 2], 2, 2) # Only one robot refills to feed the middle student
    3
    >>> feed([1, 1, 1, 2, 2], 2, 2)
    4
    >>> feed([3, 2, 1, 3, 2, 1, 1, 2, 3], 3, 3)
    6
    
    def helper(lst, p, q):
        
        if ___________________________: return ________________________________
        elif ___________________________: return ________________________________
       elif ___________________________: return ________________________________
        else:
            a = ________________________________
            b = ________________________________
            c = ________________________________
            d = ________________________________
            return ____________(a, b, c, d)

        return helper(snax, ________________________________)
```

---

1. Midterm Review Snax
(a) Two robots are handing out midterm snacks to 61A students who are lined up in the hallway. The left robot can hold $x$ snacks at once, and the right robot can hold $y$ snacks. Both robots can refill their capacity at any given time from a bottomless pit of snacks. However, when one robot (A) goes to refill snacks, the other robot (B) must wait until A returns before B continues handing out snacks. In other words, A and B must both feed a student (in full) on their respective ends of the hallway at the same time. Both robots can refill at the same time.

The list $\text{snax}$ contains the number of snacks that must be given to each student in order for that student to be satisfied. Return the minimum number of refills required for both robots to feed every student in the hallway. You can assume that the individual capacity of each robot is $\geq \max(\text{snax})$, and that each robot cannot move on from its current student until the student has been satisfied.